

GX-Force Static Program Analysis Verification Result

Document No.GX-Force_SW402

| Approval | Review | Preparation |
|--------------------------------------|--------------------------------------|---|
| Name : Engineering Div.2 Mutou | Name : Engineering Div.2 Hirao | Name : Engineering Div.2 Ikarashi |
| Date 2021/5/28 | Date 2021/5/28 | Date 2021/5/27 |

GX-Force Static Program Analysis Verification Result
(Document No.GX-Force_SW402)

| No. | Date | Version | Revised content | Remarks |
|-----|------------|---------|-----------------|---------|
| Ex. | 20XX/XX/XX | RevX.X | Create New | |
| 1 | 2021/5/27 | Rev1.0 | Create New | |
| 2 | | | | |
| 3 | | | | |
| 4 | | | | |
| 5 | | | | |
| 6 | | | | |
| 7 | | | | |
| 8 | | | | |
| 9 | | | | |
| 10 | | | | |
| 11 | | | | |
| 12 | | | | |
| 13 | | | | |
| 14 | | | | |
| 15 | | | | |
| 16 | | | | |
| 17 | | | | |
| 18 | | | | |
| 19 | | | | |
| 20 | | | | |
| 21 | | | | |
| 22 | | | | |
| 23 | | | | |
| 24 | | | | |
| 25 | | | | |
| 26 | | | | |
| 27 | | | | |
| 28 | | | | |
| 29 | | | | |

Source code static analysis results

Analytical method

- Statically analyze program with the C++test static analysis tool.
- Corresponding programs are no. 07244 and 07245.
- Categorize the analysis results into Total No. of Findings, No Problems, and Requires Correction.
 Make corrections to Requires Correction items.
- Write reason for items categorized as No Problems.
- Configure C++test as follows.
 - Compiler type
 ⇒CC-RX, CC-RL
 - Build configuration
 ⇒Same build configuration as development environment
 - Applicable rules
 ⇒Apply all MISRA-C2012 rules
- Verification level
 - Verify against MISRA C 2012 Level1, 2.
 - Information on levels
 - [1] Messages indicating major problems resulting in compiler errors
 - [2] Messages indicating program defects that potentially could result in failures
 - [3] Messages for improving maintainability, portability, and readability
 - [4] Messages for improving performance
 - [5] Messages indicating impact of changes in type handling due to porting

Analysis result

Analysis Run 1

| | |
|-----------------------|----|
| Total No. of Findings | 42 |
| Requires correction | 0 |
| No Problems | 42 |

| tool_name | name | line | path | probability | severity | tool_specific_rank | textoutput | Results | Countermeasure |
|-----------|---------------------|------|--|-------------|----------|--------------------|---|-------------|---|
| C++test | MISRA2012-RULE-17.3 | 90 | /GX-Force Sensor/cg_src/r_cg_camp.c | 1 | 2 | 2 | Prototype of function '_nop' does not precede function call | No Problems | No prob; Part of microcomputer std. lib |
| C++test | MISRA2012-RULE-17.3 | 117 | /GX-Force Sensor/cg_src/r_cg_camp.c | 1 | 2 | 2 | Prototype of function '_nop' does not precede function call | No Problems | No prob; Part of microcomputer std. lib |
| C++test | MISRA2012-RULE-17.3 | 61 | /GX-Force Sensor/cg_src/r_cg_it_user.c | 1 | 2 | 2 | Prototype of function '_EI' does not precede function call | No Problems | No prob; Part of microcomputer std. lib |
| C++test | MISRA2012-RULE-17.3 | 60 | /GX-Force Sensor/cg_src/r_cg_lvi_user.c | 1 | 2 | 2 | Prototype of function '_EI' does not precede function call | No Problems | No prob; Part of microcomputer std. lib |
| C++test | MISRA2012-RULE-17.3 | 319 | /GX-Force Sensor/cg_src/r_cg_pga_dsad.c | 1 | 2 | 2 | Prototype of function '_nop' does not precede function call | No Problems | No prob; Part of microcomputer std. lib |
| C++test | MISRA2012-RULE-17.3 | 61 | /GX-Force Sensor/cg_src/r_cg_pga_dsad_user.c | 1 | 2 | 2 | Prototype of function '_EI' does not precede function call | No Problems | No prob; Part of microcomputer std. lib |
| C++test | MISRA2012-RULE-17.3 | 64 | /GX-Force Sensor/cg_src/r_cg_sau.c | 1 | 2 | 2 | Prototype of function '_nop' does not precede function call | No Problems | No prob; Part of microcomputer std. lib |
| C++test | MISRA2012-RULE-17.3 | 65 | /GX-Force Sensor/cg_src/r_cg_sau.c | 1 | 2 | 2 | Prototype of function '_nop' does not precede function call | No Problems | No prob; Part of microcomputer std. lib |
| C++test | MISRA2012-RULE-17.3 | 66 | /GX-Force Sensor/cg_src/r_cg_sau.c | 1 | 2 | 2 | Prototype of function '_nop' does not precede function call | No Problems | No prob; Part of microcomputer std. lib |
| C++test | MISRA2012-RULE-17.3 | 67 | /GX-Force Sensor/cg_src/r_cg_sau.c | 1 | 2 | 2 | Prototype of function '_nop' does not precede function call | No Problems | No prob; Part of microcomputer std. lib |
| C++test | MISRA2012-RULE-17.3 | 85 | /GX-Force Sensor/cg_src/r_cg_systeminit.c | 1 | 2 | 2 | Prototype of function '_DI' does not precede function call | No Problems | No prob; Part of microcomputer std. lib |
| C++test | MISRA2012-RULE-17.3 | 81 | /GX-Force Sensor/prog/main.c | 1 | 2 | 2 | Prototype of function '_EI' does not precede function call | No Problems | No prob; Part of microcomputer std. lib |
| C++test | MISRA2012-RULE-17.3 | 365 | /GX-Force Sensor/prog/ram_chk.c | 1 | 2 | 2 | Prototype of function '_DI' does not precede function call | No Problems | No prob; Part of microcomputer std. lib |
| C++test | MISRA2012-RULE-17.3 | 374 | /GX-Force Sensor/prog/ram_chk.c | 1 | 2 | 2 | Prototype of function '_EI' does not precede function call | No Problems | No prob; Part of microcomputer std. lib |